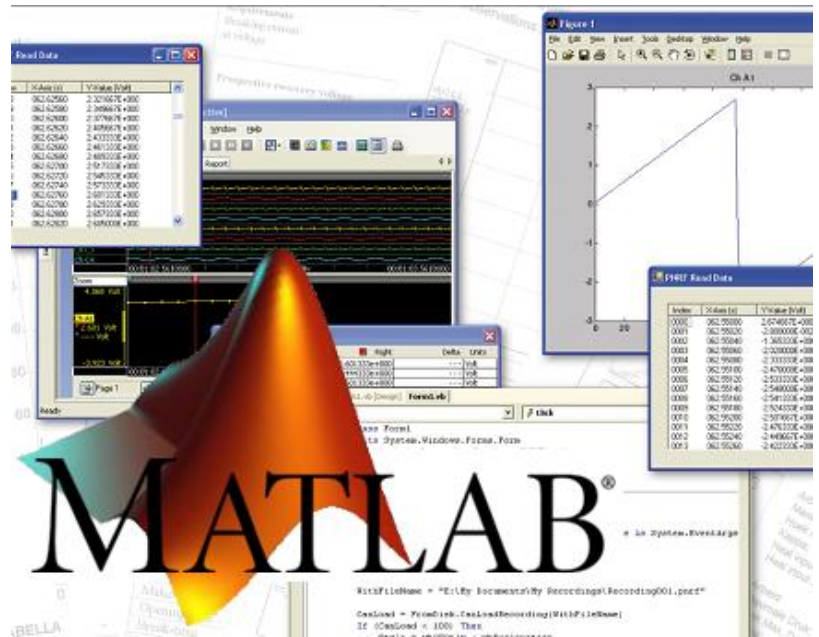


# User Manual

English



## Perception Remote Control using MATLAB® Examples

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## 1 Getting Started

Welcome to the Perception Remote Control using MATLAB®.examples document. This document contains a couple of examples showing how you can remotely control Perception from within MATLAB.

For more information on the RPC interface we refer to the help file **COMPerceptionInterfaces.chm** which can be downloaded from the HBM website.

### 1.1 Introduction

MATLAB® is a well-known language for technical computing. It integrates computation, visualization, and programming in an environment where problems and solutions are expressed in familiar mathematical notation.

MATLAB provides interfaces to clients or servers communicating via Component Object Model (COM). In this section we will describe how you can interface MATLAB to the Perception COM-RPC interface.

### 1.2 Intended audience

This documentation assumes you have sufficient knowledge of MATLAB®, this manual is NOT a tutorial on how to use MATLAB®.

This documentation also assumes you understand the HBM acquisition terminology. Understanding acquisition terminology is vital to understanding the Start, Stop, Pause recording commands and the manual Trigger command.

### 1.3 Requirements and installation

We assume you have installed MATLAB and the Perception software or the Perception COM-RPC in case you are running from a remote PC where Perception is not running.

## 2 Example 1 – Start Recording

In this example you will connect to Perception and start a recording. Before you can run the MATLAB code make sure that the Perception software program is running and connected to a GEN system or to one of the available simulators. To check if the Perception configuration is OK you only have to press the Start acquisition button and check if the recording starts. If this is the case your system is ready to be used by the MATLAB demo code. Do not forget to stop the recording in case you just started it for the above mentioned check.

```
% Create OLE Automation server to the Perception COM-RPC
Serv = actxserver('PerceptionCom.PerceptionCom');
% Set the server address to localhost, you can also use the IP address
Serv.SetServerAddress("localhost");
% Connect to Perception
Serv.ConnectToServer
% Start a recording
Serv.Start
```

## 3 Example 2 – Stop Recording

In this example you will connect to Perception and stop a running recording

```
% Create OLE Automation server to the Perception COM-RPC
Serv = actxserver('PerceptionCom.PerceptionCom');
% Set the server address to localhost, you can also use the IP address
Serv.SetServerAddress("localhost");
% Connect to Perception
Serv.ConnectToServer
% Stop a recording
Serv.Stop
```

## 4 Example 3 – Pause Recording

Shows how to pause a running recording

```
% Create OLE Automation server to the Perception COM-RPC
Serv = actxserver('PerceptionCom.PerceptionCom');
% Set the server address to localhost, you can also use the IP address
Serv.SetServerAddress("localhost");
% Connect to Perception
Serv.ConnectToServer
% Pause a recording
Serv.Pause
```

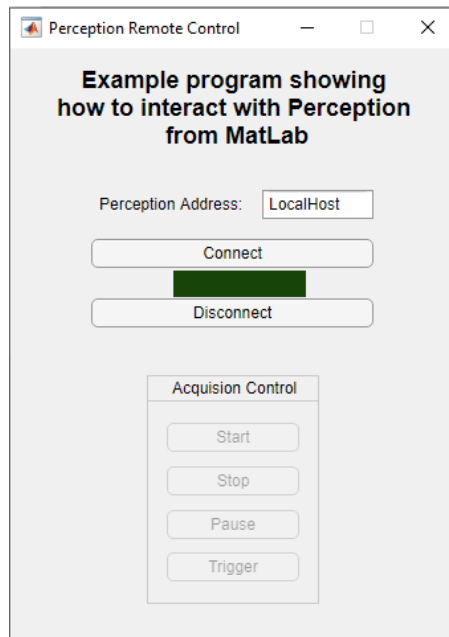
## 5 Example 4 – Manual Trigger

Shows how sent a manual trigger to Perception during a recording

```
% Create OLE Automation server to the Perception COM-RPC
Serv = actxserver('PerceptionCom.PerceptionCom');
% Set the server address to localhost, you can also use the IP address
Serv.SetServerAddress("localhost");
% Connect to Perception
Serv.ConnectToServer
% Sent a manual trigger to Perception
Serv.Trigger
```

## 6 Example 5 – GUI controlling acquisition state Perception

This demo is using the **MatLab App Designer** to create a small program which controls the Perception acquisition state.  
The program GUI looks like:



The code behind this GUI looks like

```

classdef PerceptionMatLabDemo < matlab.apps.AppBase

    % Properties that correspond to app components
    properties (Access = public)
        PerceptionRemoteControlUIFigure matlab.ui.Figure
        ConnectButton                    matlab.ui.control.Button
        Title                             matlab.ui.control.Label
        PerceptionAddressEditFieldLabel  matlab.ui.control.Label
        PerceptionAddressEditField       matlab.ui.control.EditField
        AcquisitionControlPanel          matlab.ui.container.Panel
        StartButton                      matlab.ui.control.Button
        StopButton                       matlab.ui.control.Button
        PauseButton                      matlab.ui.control.Button
        TriggerButton                   matlab.ui.control.Button
        DisconnectButton                 matlab.ui.control.Button
        ConnectionStatus                 matlab.ui.control.Label
    end

    properties (Access = private)
        Serv = 0; % Perception Server object
        IsConnected = false;
    end

    methods (Access = private)

        function updateUIConnectionStatus(app)
            if (app.IsConnected)
                app.ConnectionStatus.BackgroundColor = [0.4667 0.9686 0.302];
                app.StartButton.Enable = true;
                app.StopButton.Enable = true;
                app.PauseButton.Enable = true;
                app.TriggerButton.Enable = true;
            else
                app.ConnectionStatus.BackgroundColor = [0.090196 0.270588 0.027451];
                app.StartButton.Enable = false;
            end
        end
    end
end
    
```

```

        app.StopButton.Enable = false;
        app.PauseButton.Enable = false;
        app.TriggerButton.Enable = false;
    end
end
end

% Callbacks that handle component events
methods (Access = private)

% Code that executes after component creation
function OnStartup(app)
    UpdateUIConnectionStatus(app);
end

% Button pushed function: ConnectButton
function Connecting(app, event)
    % Create Automation server to the Perception RPC
    app.Serv = actxserver('PerceptionCom.PerceptionCom');
    % Set the server address to localhost, you can also use the IP address
    app.Serv.SetServerAddress(app.PerceptionAddressEditField.Value);
    % Connect to Perception
    app.Serv.ConnectToServer;
    app.IsConnected = true;
    UpdateUIConnectionStatus(app);
end

% Button pushed function: StartButton
function StartRecording(app, event)
    app.Serv.Start;
end

% Button pushed function: StopButton
function StopRecording(app, event)
    app.Serv.Stop;
end

% Button pushed function: PauseButton
function PausePerception(app, event)
    app.Serv.Pause;
end

% Button pushed function: TriggerButton
function TriggerPerception(app, event)
    app.Serv.Trigger;
end

% Button pushed function: DisconnectButton
function Disconnect(app, event)
    app.Serv.DisconnectFromServer;
    app.IsConnected = false;
    UpdateUIConnectionStatus(app);
end

% Close request function: PerceptionRemoteControlUIFigure
function OnClose(app, event)
    if (app.IsConnected)
        app.Serv.DisconnectFromServer;
    end
    delete(app);
end

```



```

end
end

% Component initialization
methods (Access = private)

% Create UIFigure and components
function createComponents(app)

% Create PerceptionRemoteControlUIFigure and hide until all components are created
app.PerceptionRemoteControlUIFigure = uifigure('Visible', 'off');
app.PerceptionRemoteControlUIFigure.AutoResizeChildren = 'off';
app.PerceptionRemoteControlUIFigure.Position = [400 400 338 447];
app.PerceptionRemoteControlUIFigure.Name = 'Perception Remote Control';
app.PerceptionRemoteControlUIFigure.Resize = 'off';
app.PerceptionRemoteControlUIFigure.CloseRequestFcn = createCallbackFcn(app,
@OnClose, true);
app.PerceptionRemoteControlUIFigure.Scrollable = 'on';

% Create ConnectButton
app.ConnectButton = uibutton(app.PerceptionRemoteControlUIFigure, 'push');
app.ConnectButton.ButtonPushedFcn = createCallbackFcn(app, @Connecting, true);
app.ConnectButton.Position = [62 282 213 22];
app.ConnectButton.Text = 'Connect';

% Create Title
app.Title = uilabel(app.PerceptionRemoteControlUIFigure);
app.Title.HorizontalAlignment = 'center';
app.Title.FontSize = 18;
app.Title.FontWeight = 'bold';
app.Title.Position = [5 357 334 91];
app.Title.Text = {'Example program showing '; 'how to interact with Perception ';
'from MatLab'};

% Create PerceptionAddressEditFieldLabel
app.PerceptionAddressEditFieldLabel =
uilabel(app.PerceptionRemoteControlUIFigure);
app.PerceptionAddressEditFieldLabel.HorizontalAlignment = 'right';
app.PerceptionAddressEditFieldLabel.Position = [62 319 114 22];
app.PerceptionAddressEditFieldLabel.Text = 'Perception Address: ';

% Create PerceptionAddressEditField
app.PerceptionAddressEditField = uieditfield(app.PerceptionRemoteControlUIFigure,
'text');
app.PerceptionAddressEditField.Position = [191 319 84 22];
app.PerceptionAddressEditField.Value = 'localhost';

% Create AcquisitionControlPanel
app.AcquisitionControlPanel = uipanel(app.PerceptionRemoteControlUIFigure);
app.AcquisitionControlPanel.AutoResizeChildren = 'off';
app.AcquisitionControlPanel.TitlePosition = 'centertop';
app.AcquisitionControlPanel.Title = 'Acquisition Control';
app.AcquisitionControlPanel.Position = [104 28 130 173];

% Create StartButton
app.StartButton = uibutton(app.AcquisitionControlPanel, 'push');
app.StartButton.ButtonPushedFcn = createCallbackFcn(app, @StartRecording, true);
app.StartButton.Enable = 'off';
app.StartButton.Position = [15 115 100 22];
app.StartButton.Text = 'Start';
    
```

```

% Create StopButton
app.StopButton = uibutton(app.AcquisitionControlPanel, 'push');
app.StopButton.ButtonPushedFcn = createCallbackFcn(app, @StopRecording, true);
app.StopButton.Enable = 'off';
app.StopButton.Position = [15 82 100 22];
app.StopButton.Text = 'Stop';

% Create PauseButton
app.PauseButton = uibutton(app.AcquisitionControlPanel, 'push');
app.PauseButton.ButtonPushedFcn = createCallbackFcn(app, @PausePerception, true);
app.PauseButton.Enable = 'off';
app.PauseButton.Position = [15 49 100 22];
app.PauseButton.Text = 'Pause';

% Create TriggerButton
app.TriggerButton = uibutton(app.AcquisitionControlPanel, 'push');
app.TriggerButton.ButtonPushedFcn = createCallbackFcn(app, @TriggerPerception,
true);
app.TriggerButton.Enable = 'off';
app.TriggerButton.Position = [15 17 100 22];
app.TriggerButton.Text = 'Trigger';

% Create DisconnectButton
app.DisconnectButton = uibutton(app.PerceptionRemoteControlUIFigure, 'push');
app.DisconnectButton.ButtonPushedFcn = createCallbackFcn(app, @Disconnect, true);
app.DisconnectButton.Position = [62 237 213 22];
app.DisconnectButton.Text = 'Disconnect';

% Create ConnectionStatus
app.ConnectionStatus = uilabel(app.PerceptionRemoteControlUIFigure);
app.ConnectionStatus.BackgroundColor = [0.0902 0.2706 0.0275];
app.ConnectionStatus.Position = [124 260 100 20];
app.ConnectionStatus.Text = '';

% Show the figure after all components are created
app.PerceptionRemoteControlUIFigure.Visible = 'on';
end
end

% App creation and deletion
methods (Access = public)

% Construct app
function app = PerceptionMatLabDemo

% Create UIFigure and components
createComponents(app)

% Register the app with App Designer
registerApp(app, app.PerceptionRemoteControlUIFigure)

% Execute the startup function
runStartupFcn(app, @OnStartup)

if nargin == 0
    clear app
end
end
end

```

```
% Code that executes before app deletion
function delete(app)

    % Delete UIFigure when app is deleted
    delete(app.PerceptionRemoteControlUIFigure)
end
end
end
```

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